

DMBHR Specification

Kuo-Yang Tu ^{a,1}, Ming-Fang Tsai^a, Wen-Chin Chang^a, Cheng-Liang Chen^a,
Hsiang-Pin Yang^a,

^a Institute of System Information and Control,
National Kaohsiung First University of Science and Technology
tuky@ccms.nkfust.edu.tw



Robot name	DMBHR
DOFs	2*6 (legs) + 2*3 (arms) + 1*2 (head)
Number of motors	24
Type of motors	RX64 and AX12
Processing	1 AVR (motion) + 1 AVR (sensors) + 1*2G Pentium
Height	1.3 m
Weight	9.6 Kg
Walking Speed	0.50 m/sec
Camera	2*CMOS sensors 640*480 resolution
Sensors	Motion sensors and force sensors (strain guage)
Other Spec.	None

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