## **Kaobotics Specification**

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Robot name Kaobotics

DOFs 2\*6 (legs) + 2\*3 (arms) + 1\*2 (head)

Number of motors 24

Type of motors RX64 and AX12

Processing 1 AVR (motion) + 1 AVR (sensors) + 1\*2G Pentium

Height 1.3 m Weight 9.6 Kg Walking Speed 0.50 m/sec

Camera 2\*CMOS sensors 640\*480 resolution

Sensors Motion sensors and force sensors (strain guage)

Other Spec. None

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