## BI-Forward Robot Specifications 2011



Robot Name
Height
Width
Foot dimension $7 \text{cm x } 11 \text{m} =$
Walking Speed
Degrees of freedom
Motors 20 servo motors
Computing Unit
Camera
Sensors

Mark 1 42cm 22cm 77cm about 15cm/s 20 KRS-2555HV Intel Atom 1.6GHZ Single Creative Live! mounted on the neck which has 2 degrees of freedom 1 gyroscope and 1 accelerometer

Sensors