Robot Name: GRM-Strong
Height: 583mm
Weight: 5341g
Walking speed: 0.35m/s
Number of degrees of freedom: 21
Joint torques: RX64, 64.4kgf/cm, RX28: 28.8kgf/cm
Type of sensors used: Logitech Quickcam 5000, ADCL203 accelerometer
Computing units: PC104 AMD Ix800 500MHz
Source: Polymer Lithium Ion Batteries, special Power Module
Capacity: full-load operation 25min
gait locomotion: Current planning, global motion
the control of motor: ARM+Real Time Operating System, 100MHz
image acquisition: 640*480, 15f/s
the software of gait: MotionDebug4.3 support the wireless debug
memory: 256M internal memory+4Gexternal storage
network: cortex-M3 LPC1768
operating system: Linux
Robot Name: GRM-Diors  
Height: 583mm  
Weight: 5338g  
Walking speed: 0.45m/s  
Number of degrees of freedom: 21  
Joint torques: RX64, 64.4kgf/cm, RX28: 28.8kgf/cm  
Type of sensors used: Logitech Quickcam 5000, IMU module, digital compass module  
Computing units: Samsung S5pv210  
Source: Polymer Lithium Ion Batteries, special Power Module  
Capacity: full-load operation 25min  
gait locomotion: Current planning, global motion  
the control of motor: ARM+Real Time Operating System, 100MHz  
image acquisition: 640*480,15f/s  
the software of gait: MotionDebug4.3, support the wireless debug  
memory: 512M RAM Flash, 1G SLC Nand Flash  
network: cortex-M3 LPC1768  
operating system: Linux