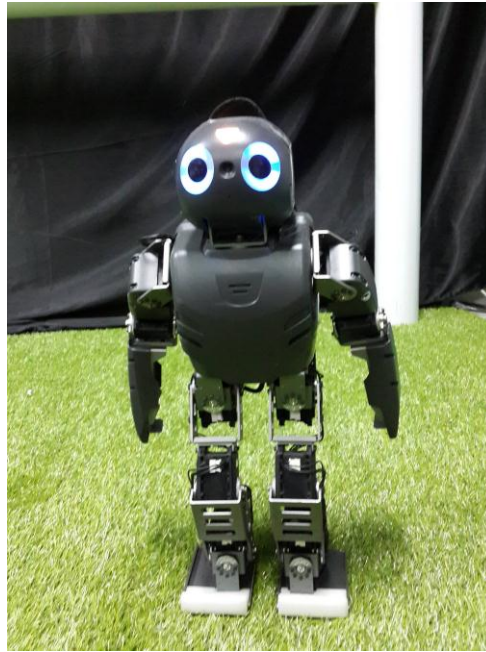


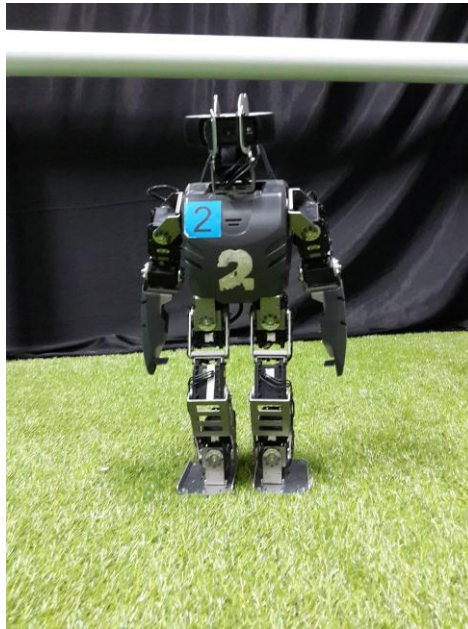
ICHIRO TEAM

Robot #1



CPU	Main Controller	fitPC2i (Intel Atom 1.6GHz)
	Sub Controller	CM-730(ARM CortexM3 STM32F103RE 72MHz)
Actuator	Head	2 Dynamixel MX-28
	Arm	2 x 3 Dynamixel MX-28
	Leg	2 x 6 Dynamixel MX-28
Sensor	Gyroscope	LYPF540AH
	Accelerometer	ADXL335
	Camera	Logitech C905
	Heading	APM
Power	Battery LiPo 3 cell 2200 mAh	
Dimension	Height	454.5 mm
	Foot	66.0 mm x 104.0 mm
	Leg	219.5 mm
	Arm	454.5 mm
	Weight	2.9 kg
DOF	Head	2 DOF
	Arm	2 x 3 DOF
	Leg	2 x 6 DOF
Motion	Walking Speed	35.0 cm/sec

Robot #2 & Robot #3



CPU	Main Controller	fitPC2i (Intel Atom 1.6GHz)
	Sub Controller	CM-730(ARM CortexM3 STM32F103RE 72MHz)
Actuator	Head	2 Dynamixel MX-28
	Arm	2 x 3 Dynamixel MX-28
	Leg	2 x 6 Dynamixel MX-28
Sensor	Gyroscope	LYPF540AH
	Accelerometer	ADXL335
	Camera	Logitech C920
	Heading	APM
Power	Battery LiPo 3 cell 2200 mAh	
Dimension	Height	454.5 mm
	Foot	66.0 mm x 104.0 mm
	Leg	219.5 mm
	Arm	454.5 mm
	Weight	2.9 kg
DOF	Head	2 DOF
	Arm	2 x 3 DOF
	Leg	2 x 6 DOF
Motion	Walking Speed	35.0 cm/sec