

Robot Specifications

University of Toronto Robotics Association



Name	Béz
Height	45 cm
Weight	~2.4 kg
Walking Speed	10 cm/s
Degrees of Freedom	16 total; 6 per leg and 2 per arm
Motors	16 Dynamixel AX-12A servo motors
Sensors	MPU6050 IMU Logitech C920 HD camera
Computing Units	NVIDIA Jetson TX2 (Ubuntu 16.04) ARM Cortex-M7 STM32H743ZITx (FreeRTOS)



